

Now suppose that a **small** amount of damping is present in the system. Mathematically this is represented by $\gamma \equiv (b/2M) < \omega$, hence $\sqrt{\gamma^2 - \omega^2} = i\sqrt{\omega^2 - \gamma^2}$, with purely real $\sqrt{\omega^2 - \gamma^2} > 0$. We define $\omega'^2 \equiv \omega^2 - \gamma^2$ or equivalently $\omega' \equiv \sqrt{\omega^2 - \gamma^2} > 0$. Thus, for **under-damped** 1-D harmonic motion, with $0 < \gamma \equiv (b/2M) < \omega$, we see that $\zeta = -\gamma \pm \sqrt{\gamma^2 - \omega^2} = -\gamma \pm i\sqrt{\omega^2 - \gamma^2} = -\gamma \pm i\omega'$, and thus the **physical** solution for **under-damped** 1-D harmonic motion, for our **initial** conditions is given by: $x(t) = x_0 e^{\zeta t} = x_0 e^{-\gamma t} \cos(\omega' t) = \frac{1}{2} x_0 e^{-\gamma t} (e^{i\omega' t} + e^{-i\omega' t})$ where the **damping constant** $0 < \gamma \equiv (b/2M) < \omega$ and $0 < \omega' \equiv \sqrt{\omega^2 - \gamma^2} < \omega$. The motion is **exponentially** damped as time increases, with **damping time constant** $\tau_d \equiv 1/\gamma = (2M/b)$ (seconds), where the **envelope** of the 1-D oscillation falls to $1/e = e^{-1} \approx 0.3679$ of its initial value at time $t = \tau_d \equiv 1/\gamma = (2M/b)$ (seconds), as shown in the figure below:

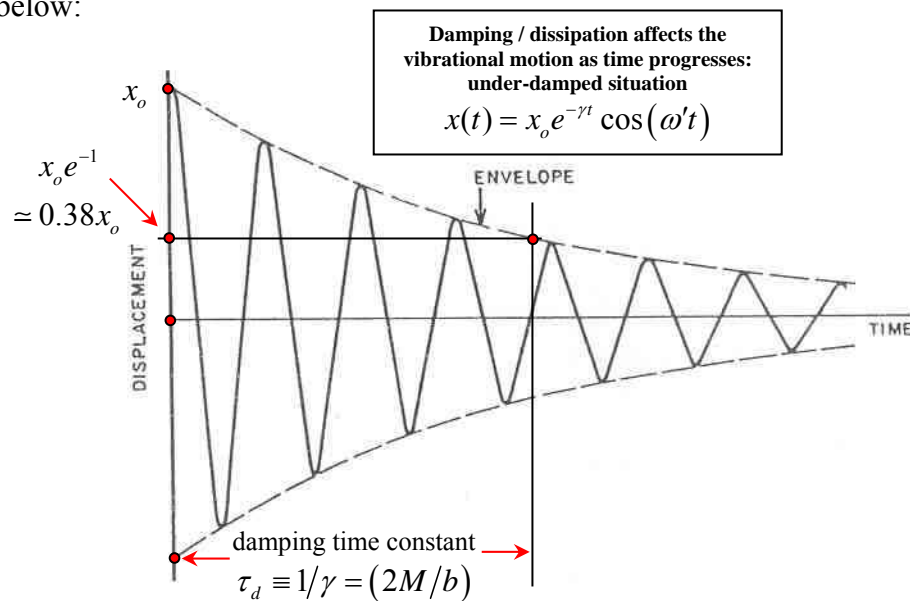


FIG. 3. Graph of displacement versus time for a damped vibration.

Dissipative processes/friction tends to **lower** the frequency of oscillation of a vibrating system, as can be seen from the relation $0 < \omega' = \sqrt{\omega^2 - \gamma^2} < \omega$. Small damping corresponds to a slight decrease in the oscillation frequency from its “natural” un-damped value of $\omega = \sqrt{k/M}$.

If we now imagine slowly increasing the damping to “heavy” damping – eventually there will be no oscillation(s) at all! When $\gamma = \omega$, the system is said to be **critically damped**, and $\zeta = -\gamma$, and the corresponding **critically-damped** motion is a purely-decaying exponential with time:

$x(t) = x_0 e^{-\gamma t}$. When $\gamma > \omega$, the system is said to be **over-damped**, and $\sqrt{\gamma^2 - \omega^2} > 0$.

Here, $\zeta = -\gamma \pm \sqrt{\gamma^2 - \omega^2}$, but the **physical** solution is: $\zeta = -\gamma + \sqrt{\gamma^2 - \omega^2} = -\gamma \left(1 - \sqrt{1 - (\omega/\gamma)^2}\right)$.

The **over-damped** motion is again a decaying exponential with time: $x(t) = x_0 e^{\zeta t} = x_0 e^{-\gamma \left(1 - \sqrt{1 - (\omega/\gamma)^2}\right) t}$.