

Transducers Used for the Measurement of Particle Velocity:

How can one measure particle velocity $\vec{u}(\vec{r}, t)$? There are two ways – one is to build a device which is **directly** sensitive to particle velocity, the other is to exploit what the {linearized} Euler equation for inviscid fluid flow tells us:

$$\frac{\partial \vec{u}(\vec{r}, t)}{\partial t} = -\frac{1}{\rho_o} \vec{\nabla} \tilde{p}(\vec{r}, t)$$

If we focus, for the moment on **one** spatial component of this equation, *e.g.* in the \hat{z} -direction, this equation in Cartesian coordinates becomes simply:

$$\frac{\partial \tilde{u}_z(\vec{r}, t)}{\partial t} = -\frac{1}{\rho_o} \frac{\partial \tilde{p}(\vec{r}, t)}{\partial z} \Rightarrow -\frac{1}{\rho_o} \frac{\Delta_z \tilde{p}(\vec{r}, t)}{\Delta z}$$

Euler's equation tells us that if we measure the pressure **gradient** {an over-pressure **difference**} $\Delta_z \tilde{p}(\vec{r}, t) \equiv \tilde{p}(z_2, t) - \tilde{p}(z_1, t)$ over a **small** separation distance $\Delta z \equiv z_2 - z_1$ (*n.b.* with $\Delta z \ll \lambda$), then Euler's equation tells us that the pressure gradient is proportional to the time rate of change of the z -component of the particle velocity $\partial \tilde{u}_z(\vec{r}, t) / \partial t$! Thus, if we integrate the pressure gradient $\Delta_z \tilde{p}(\vec{r}, t) / \Delta z$ with respect to time, the integral is **proportional** to the z -component of the particle velocity:

$$\tilde{u}_z(\vec{r}, t) = -\frac{1}{\rho_o \Delta z} \int_{t'=-\infty}^{t'=t} \Delta_z \tilde{p}(\vec{r}, t') dt' = -\frac{1}{\rho_o (z_2 - z_1)} \int_{t'=-\infty}^{t'=t} [\tilde{p}(z_2, t') - \tilde{p}(z_1, t')] dt'$$

Likewise, if we then also measure the instantaneous pressure gradients $\Delta_x \tilde{p}(\vec{r}, t)$ ($\Delta_y \tilde{p}(\vec{r}, t)$) over small distances Δx (Δy) in the \hat{x} (\hat{y})-directions, respectively, and then integrate these two signals, then we also obtain measurements of:

$$\tilde{u}_x(\vec{r}, t) = -\frac{1}{\rho_o \Delta x} \int_{t'=-\infty}^{t'=t} \Delta_x \tilde{p}(\vec{r}, t') dt' = -\frac{1}{\rho_o (x_2 - x_1)} \int_{t'=-\infty}^{t'=t} [\tilde{p}(x_2, t') - \tilde{p}(x_1, t')] dt'$$

and:
$$\tilde{u}_y(\vec{r}, t) = -\frac{1}{\rho_o \Delta y} \int_{t'=-\infty}^{t'=t} \Delta_y \tilde{p}(\vec{r}, t') dt' = -\frac{1}{\rho_o (y_2 - y_1)} \int_{t'=-\infty}^{t'=t} [\tilde{p}(y_2, t') - \tilde{p}(y_1, t')] dt'$$

To measure a pressure gradient $\Delta_r \tilde{p}(\vec{r}, t) = \tilde{p}(\vec{r}_2, t) - \tilde{p}(\vec{r}_1, t)$ between two points one can use *e.g.* two {hopefully} identical/perfectly frequency/phase-matched microphones (with $S_{mic1} = S_{mic2}$), and then use (or build) a (precision) low-noise **differential** preamp to take the voltage difference $\Delta \tilde{V}(t) = \tilde{V}_{mic2}(\vec{r}_2, t) - \tilde{V}_{mic1}(\vec{r}_1, t)$ between the two signals, since:

$$\Delta_r \tilde{p}(\vec{r}, t) = \tilde{p}(\vec{r}_2, t) - \tilde{p}(\vec{r}_1, t) = \frac{\tilde{V}_{mic2}(\vec{r}_2, t)}{S_{mic2}} - \frac{\tilde{V}_{mic1}(\vec{r}_1, t)}{S_{mic1}}$$