

The pressure/particle velocity fields in proximity to the actual sound source inside the duct are determined largely by the image source(s) nearest to the actual sound source; the solution converges rapidly as the number of image sources is increased. However, accuracy in calculating the pressure / particle velocity fields far from the actual sound source (*i.e.* further down the duct,  $\Delta x \gg a$ ) requires increasingly larger numbers of image sources to be included.

The image source technique is widely used e.g. in computational modeling of room acoustics.

The complex <u>frequency-domain</u> 2-D vector specific impedance/admittance, acoustic energy flow velocity, acoustic intensity and purely real, scalar energy densities, *etc.* inside the duct can all be computed (most easily accomplished *e.g.* via numerical computation...) from their definitions, for a given sound source & frequency:

$$\vec{\tilde{z}}_{a}(x,y,\omega) = \frac{\tilde{p}(x,y,\omega)}{\vec{\tilde{u}}(x,y,\omega)} = \frac{\tilde{p}(x,y,\omega) \cdot \vec{\tilde{u}}^{*}(x,y,\omega)}{\left|\vec{\tilde{u}}(x,y,\omega)\right|^{2}} \quad (\Omega_{a}) \quad \text{and:} \quad \vec{\tilde{y}}(x,y,\omega) = \frac{\vec{\tilde{u}}(x,y,\omega)}{p(x,y,\omega)} \quad (\Omega_{a}^{-1})$$

$$\vec{\tilde{c}}_a(x, y, \omega) = \frac{1}{\rho_o} \vec{\tilde{z}}_a(x, y, \omega) (m/s) \quad \text{and:} \quad \vec{\tilde{I}}_a(x, y, \omega) = \frac{1}{2} \tilde{p}(x, y, \omega) \cdot \vec{\tilde{u}}^*(x, y, \omega) (Watts/m^2)$$