

Obviously, if we carry out *e.g.* a simple rotation of our local 3-D coordinate system, the individual x, y, z components of $\vec{y}_a(\vec{r}, t)$ will change accordingly, however the magnitude

$$|\vec{y}_a(\vec{r}, t)| = \sqrt{\vec{y}_a(\vec{r}, t) \cdot \vec{y}_a^*(\vec{r}, t)} = \sqrt{|\tilde{y}_{a_x}(\vec{r}, t)|^2 + |\tilde{y}_{a_y}(\vec{r}, t)|^2 + |\tilde{y}_{a_z}(\vec{r}, t)|^2} \text{ will **not** change.}$$

Likewise, the individual x, y, z components of $\vec{z}_a(\vec{r}, t)$ will change accordingly under a simple rotation of our local 3-D coordinate system, however the magnitude

$$|\vec{z}_a(\vec{r}, t)| = \sqrt{\vec{z}_a(\vec{r}, t) \cdot \vec{z}_a^*(\vec{r}, t)} = \sqrt{|\tilde{z}_{a_x}(\vec{r}, t)|^2 + |\tilde{z}_{a_y}(\vec{r}, t)|^2 + |\tilde{z}_{a_z}(\vec{r}, t)|^2} \text{ will **not** change.}$$

We thus write the complex 3-D vector **specific** acoustic impedance $\vec{z}_a(\vec{r}, t)$, *e.g.* in Cartesian coordinates as follows:

$$\begin{aligned} \vec{z}_a(\vec{r}, t) &\equiv \frac{\tilde{p}(\vec{r}, t)}{\vec{\tilde{u}}(\vec{r}, t)} = \tilde{z}_{a_x}(\vec{r}, t)\hat{x} + \tilde{z}_{a_y}(\vec{r}, t)\hat{y} + \tilde{z}_{a_z}(\vec{r}, t)\hat{z} \\ &= \frac{\tilde{p}(\vec{r}, t) \cdot \vec{\tilde{u}}^*(\vec{r}, t)}{\vec{\tilde{u}}(\vec{r}, t) \cdot \vec{\tilde{u}}^*(\vec{r}, t)} = \frac{\tilde{p}(\vec{r}, t)\tilde{u}_x^*(\vec{r}, t)}{|\vec{\tilde{u}}(\vec{r}, t)|^2} \\ &= \frac{\tilde{p}(\vec{r}, t)[\tilde{u}_x^*(\vec{r}, t)\hat{x} + \tilde{u}_y^*(\vec{r}, t)\hat{y} + \tilde{u}_z^*(\vec{r}, t)\hat{z}]}{|\vec{\tilde{u}}(\vec{r}, t)|^2} \\ &= \frac{\tilde{p}(\vec{r}, t)[\tilde{u}_x^*(\vec{r}, t)\hat{x} + \tilde{u}_y^*(\vec{r}, t)\hat{y} + \tilde{u}_z^*(\vec{r}, t)\hat{z}]}{|\tilde{u}_x(\vec{r}, t)|^2 + |\tilde{u}_y(\vec{r}, t)|^2 + |\tilde{u}_z(\vec{r}, t)|^2} \end{aligned}$$

$$\text{where: } \tilde{z}_{a_x}(\vec{r}, t) = \frac{\tilde{p}(\vec{r}, t)\tilde{u}_x^*(\vec{r}, t)}{|\vec{\tilde{u}}(\vec{r}, t)|^2}, \quad \tilde{z}_{a_y}(\vec{r}, t) = \frac{\tilde{p}(\vec{r}, t)\tilde{u}_y^*(\vec{r}, t)}{|\vec{\tilde{u}}(\vec{r}, t)|^2}, \quad \tilde{z}_{a_z}(\vec{r}, t) = \frac{\tilde{p}(\vec{r}, t)\tilde{u}_z^*(\vec{r}, t)}{|\vec{\tilde{u}}(\vec{r}, t)|^2}$$

Hence, the technical/mathematical issue here is the rationalization of an arbitrary, “generic” complex reciprocal 3-D vector quantity:

$$\vec{u}^{-1} = \frac{1}{\vec{u}} = \frac{\vec{u}^*}{\vec{u} \cdot \vec{u}^*} = \frac{\vec{u}^*}{|\vec{u}|^2}$$

paralleling that which is done for an arbitrary, “generic” complex reciprocal scalar quantity:

$$\tilde{p}^{-1} = \frac{1}{\tilde{p}} = \frac{\tilde{p}^*}{\tilde{p} \cdot \tilde{p}^*} = \frac{\tilde{p}^*}{|\tilde{p}|^2}$$

It can be seen that indeed: $|\vec{y}_a(\vec{r}, t)| = \frac{|\vec{\tilde{u}}(\vec{r}, t)|}{|\tilde{p}(\vec{r}, t)|} = \frac{|\vec{\tilde{u}}(\vec{r}, t)|}{|\tilde{p}(\vec{r}, t)|} = \frac{1}{|\vec{z}_a(\vec{r}, t)|}$, and also that: