

Speed: = instantaneous time rate of change of position = magnitude of velocity:

$$v(\vec{r}, t) = |\vec{v}(\vec{r}, t)| = \sqrt{v_x^2(\vec{r}, t) + v_y^2(\vec{r}, t) + v_z^2(\vec{r}, t)} \quad (\text{Cartesian Coordinates})$$

Thus, Velocity = instantaneous speed in a given direction, e.g. in east direction, or up, or down, etc.

From calculus, we know that the instantaneous velocity $\vec{v}(\vec{r}, t)$ is the partial derivative of the instantaneous position with respect to time (= instantaneous slope of $\vec{r}(t)$ vs. t graph):

$$\text{Velocity: } \vec{v}(\vec{r}, t) = \frac{\partial \vec{r}(t)}{\partial t} = \frac{\partial x(t)}{\partial t} \hat{x} + \frac{\partial y(t)}{\partial t} \hat{y} + \frac{\partial z(t)}{\partial t} \hat{z} = v_x(\vec{r}, t) \hat{x} + v_y(\vec{r}, t) \hat{y} + v_z(\vec{r}, t) \hat{z}$$

Acceleration: = instantaneous time rate of change of velocity, and a direction (up, down, east, west, etc.) specifying the direction in which the time rate of change of velocity is occurring.
3-D vector quantity (*SI* units = meters per second squared, i.e. m/s^2)

Speed increasing with time — accelerating
Speed decreasing with time — decelerating

$$\text{Acceleration: } \vec{a}(\vec{r}, t) = a_x(\vec{r}, t) \hat{x} + a_y(\vec{r}, t) \hat{y} + a_z(\vec{r}, t) \hat{z} = \partial \vec{v}(\vec{r}, t) / \partial t \quad (\text{Cartesian Coordinates})$$

$$\text{Magnitude (size) of instantaneous acceleration: } a(\vec{r}, t) = |\vec{a}(\vec{r}, t)| = \sqrt{a_x^2(\vec{r}, t) + a_y^2(\vec{r}, t) + a_z^2(\vec{r}, t)}$$

From calculus, we also know that the instantaneous acceleration is the partial derivative of the instantaneous velocity with respect to time (= instantaneous slope of $\vec{v}(\vec{r}, t)$ vs. t graph):

$$\text{Acceleration: } \vec{a}(\vec{r}, t) = \frac{\partial \vec{v}(\vec{r}, t)}{\partial t} = \frac{\partial v_x(\vec{r}, t)}{\partial t} \hat{x} + \frac{\partial v_y(\vec{r}, t)}{\partial t} \hat{y} + \frac{\partial v_z(\vec{r}, t)}{\partial t} \hat{z} = a_x(\vec{r}, t) \hat{x} + a_y(\vec{r}, t) \hat{y} + a_z(\vec{r}, t) \hat{z}$$

Motion in 3-D is independent in x - y - z directions for a free particle (unless geometrically constrained somehow – e.g. bead on a helix or circular ring):

3-D Equations of motion of a free particle with constant acceleration: $\vec{a}(\vec{r}, t) = \vec{a}_o$

$$\vec{v}(\vec{r}, t) = \vec{v}_o + \vec{a}_o t \quad (v_o = 3\text{-D vector velocity at time } t = 0)$$

$$\vec{r}(t) = \vec{r}_o + \vec{v}_o t + \frac{1}{2} \vec{a}_o t^2 \quad (r_o = 3\text{-D vector position at time } t = 0)$$

Short-hand way to write out the separate x - y - z equations of motion (decouple for a free particle):

$$\begin{array}{|l} v_x(\vec{r}, t) = v_{ox} + a_{ox} t \\ v_y(\vec{r}, t) = v_{oy} + a_{oy} t \\ v_z(\vec{r}, t) = v_{oz} + a_{oz} t \end{array} \quad \begin{array}{|l} x(t) = x_o + v_{ox} t + \frac{1}{2} a_{ox} t^2 \\ y(t) = y_o + v_{oy} t + \frac{1}{2} a_{oy} t^2 \\ z(t) = z_o + v_{oz} t + \frac{1}{2} a_{oz} t^2 \end{array}$$