## Angular Momentum & Uncertainty Principle

Note that  $L^2 = l(l+1)\hbar^2$  not  $(l\hbar)^2$ 

Also, we describe angular momentum using only two numbers, *l* and *m*.

- Q: Why can't we specify all three components (e.g., L = (0,0,l) so that  $L^2 = l^2$ ?
- A: The uncertainty principle doesn't allow us to know that both  $L_x = 0$ and  $L_y = 0$  unless  $L_z = 0$  also.

Proof by contradiction: Assume L =(0,0,*l*).  $\vec{L} = \vec{r} \times \vec{p}$ , so if *L* points along the z-axis, both *r* and *p* lie in the x-y plane. This means that  $\Delta z = 0$  and  $\Delta p_z = 0$ , violating the uncertainty principle. Thus, L must have a nonzero L<sub>x</sub> or L<sub>y</sub>, making L<sup>2</sup> somewhat larger.

We can't specify all three components of the angular momentum vector.

This logic only works for  $L \neq 0$ . L = (0,0,0) is allowed. It's the s-state.

All physical quantities are subject to uncertainty relations, not just position and momentum.