

## Observer Pole Placement, O/C Duality Version

Given an **observable** pair  $(A, C)$ :

1. For  $F = A^T$ ,  $G = C^T$ , consider the system  $\dot{x} = Fx + Gu$  (this system is controllable).
2. Use our earlier procedure to find  $K$ , such that

$$F - GK = A^T - C^T K$$

has desired eigenvalues.

3. Then

$$\text{eig}(A^T - C^T K) = \text{eig}(A^T - C^T K)^T = \text{eig}(A - K^T C),$$

so  $L = K^T$  is the desired output injection matrix.

**Final answer:** use the observer

$$\begin{aligned}\dot{\hat{x}} &= (A - LC)\hat{x} + Ly \\ &= (A - K^T C)\hat{x} + K^T y.\end{aligned}$$