

## From State-Space to Transfer Function

$$\dot{x} = Ax + Bu$$

$$y = Cx + Du$$

$$x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}, \quad u = \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_m \end{pmatrix}, \quad y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_p \end{pmatrix}$$

Recall matrix-vector multiplication:

$$\begin{aligned} \dot{x}_i &= (Ax)_i + (Bu)_i \\ &= \sum_{j=1}^n a_{ij}x_j + \sum_{k=1}^m b_{ik}u_k \end{aligned}$$

$$\begin{aligned} y_\ell &= (Cx)_\ell + (Du)_\ell \\ &= \sum_{j=1}^n c_{\ell j}x_j + \sum_{k=1}^m d_{\ell k}u_k \end{aligned}$$