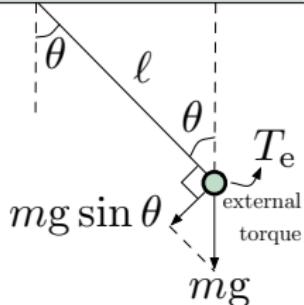


Example 3: Pendulum



Newton's 2nd law (rotational motion):

$$\underbrace{T}_{\substack{\text{total} \\ \text{torque}}} = \underbrace{J}_{\substack{\text{moment} \\ \text{of inertia}}} \underbrace{\alpha}_{\substack{\text{angular} \\ \text{acceleration}}}$$

= pendulum torque + external torque

$$\text{pendulum torque} = \underbrace{-mg \sin \theta}_{\substack{\text{force}}} \cdot \underbrace{\ell}_{\substack{\text{lever arm}}}$$

$$\text{moment of inertia } J = m\ell^2$$

$$-mgl \sin \theta + T_e = m\ell^2 \ddot{\theta}$$

$$\ddot{\theta} = -\frac{g}{\ell} \sin \theta + \frac{1}{m\ell^2} T_e \quad (\text{nonlinear equation})$$