

## General Linearization Procedure

- ▶ Start from nonlinear state-space model

$$\dot{x} = f(x, u)$$

- ▶ Find **equilibrium point**  $(x_0, u_0)$  such that  $f(x_0, u_0) = 0$

*Note:* different systems may have different equilibria, not necessarily  $(0, 0)$ , so we need to shift variables:

$$\begin{aligned}\underline{x} &= x - x_0 & \underline{u} &= u - u_0 \\ \underline{f}(\underline{x}, \underline{u}) &= f(\underline{x} + x_0, \underline{u} + u_0) = f(x, u)\end{aligned}$$

Note that the transformation is *invertible*:

$$x = \underline{x} + x_0, \quad u = \underline{u} + u_0$$