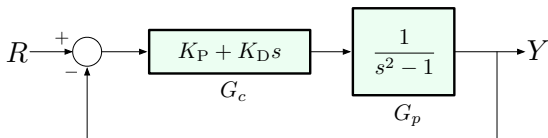


## Example

PD control of an unstable 2nd-order plant



$$\frac{Y}{R} = \frac{G_c G_p}{1 + G_c G_p} \quad \text{poles: } 1 + G_c(s)G_p(s) = 0$$

$$1 + (K_P + K_D s) \left( \frac{1}{s^2 - 1} \right) = 0$$

We will examine the impact of varying  $K = K_D$ , assuming the ratio  $K_P/K_D$  *fixed*.