

The Backward Algorithm

Observation: $p(o_1 \dots o_T | \lambda) = \sum_{i=1}^N \sum_{S_2 \dots S_T} p(o_1 \dots o_T, S_1 = s_i, S_2 \dots S_T)$

Algorithm: $= \sum_{i=1}^N \pi_i b_i(o_1) \sum_{S_2 \dots S_T} p(o_2 \dots o_T, S_2 \dots S_T | S_1 = s_i)$ **($o_1 \dots o_t$ already generated)**

$$\beta_t(i) = \sum_{S_{t+1} \dots S_T} p(o_{t+1} \dots o_T, S_{t+1} \dots S_T | S_t = s_i)$$

← **Starting from state s_i
Generating $o_{t+1} \dots o_T$**

$$= \sum_{S_{t+1} \dots S_T} p(o_{t+2} \dots o_T, S_{t+2} \dots S_T | S_{t+1}) p(S_{t+1} | S_t = s_i) p(o_{t+1} | S_{t+1})$$

$$= \sum_{j=1}^N a_{ij} b_j(o_{t+1}) \sum_{S_{t+2} \dots S_T} p(o_{t+2} \dots o_T, S_{t+2} \dots S_T | S_{t+1} = s_j)$$

$$= \sum_{j=1}^N a_{ij} b_j(o_{t+1}) \beta_{t+1}(j)$$

Complexity: $O(TN^2)$

The data likelihood is

$$p(o_1 \dots o_T | \lambda) = \sum_{i=1}^N \pi_i b_i(o_1) \beta_1(i) = \sum_{i=1}^N \alpha_1(i) \beta_1(i) = \sum_{i=1}^N \alpha_t(i) \beta_t(i) \text{ for any } t$$